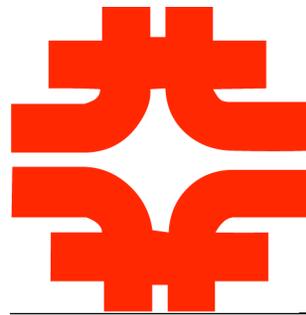


Data Acquisition, Calibration & Foregrounds

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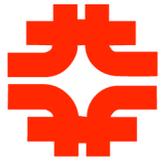
Data Acquisition

- We imagine an array that produces
 - 4096 channels of data
 - 500 MS/sec (Mega-Samples/sec) per channel
 - 32 bits per sample
- A few Gb size DDR3 SDRAM memory chips *per channel* should be sufficient.
 - Separate read/write chips
 - Double buffer for accumulate/readout



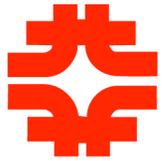
Data Acquisition (con't)

- A single computer PCI express can accommodate 32 bits at 500 MS/sec and is therefore adequate for the entire system if a minimum of 4096 accumulations is made.
- A single disk drive could maintain a rate of 100 MB/sec. This would require a minimum of $20 \times 4096 = 81920$ accumulations (about 10 sec for a record length of 131 μ sec)
- Total amount of data per day (18 hrs) is 6.5 TB
- Data disks can be “mailed” to a remote site (s).



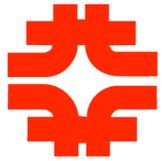
Data Monitoring

- Sequence data acquisition
 - Survey data
 - Calibration data
- Calculate & update calibration constants
- Monitor
 - ADC: mean, rms, minimum, maximum
 - Digital processing: exceptions
 - Power distribution: voltages & currents
 - Temperatures?
- Alarm on abnormal conditions



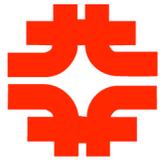
Calibration the Problem

- We need to calibrate
 - ❑ Frequency response for foreground subtraction
 - ❑ Polarization response for foreground subtraction
 - ❑ Spatial response for BAO power spectrum (Is spatial response necessary for foregrounds?)
- Requirements
 - ❑ Frequency of calibration (~minutes?)
 - ❑ Accuracy of frequency calibration (10^{-5} ?)
 - ❑ Accuracy of spatial calibration (10%?)



Calibration: Solutions

- The ultimate goal is to have a good model of the instrument response. We don't really care what the data look like if we can back out the correct sky model.
- Some features of the instrument have to be calibrated in real time: Gain and phase equalization of different channels (?)
- Some features are difficult or impossible to calibrate in real time: Antenna shape parameters



Instrument Model

- Each electronics channel has a complex gain that varies rapidly (faster than 1 day) with time.
- Each antenna has average properties that are fixed in time (changes much slower than 1 day).
 - ❑ Identical antennas with pointing errors?
 - ❑ Assume perfect spacing?
 - ❑ Antenna gain variations (field pattern shape)?
 - ❑ Can antenna-LNA mismatches and feed-to-feed coupling be compensated with an overall gain?



Calibration-Artificial Sources

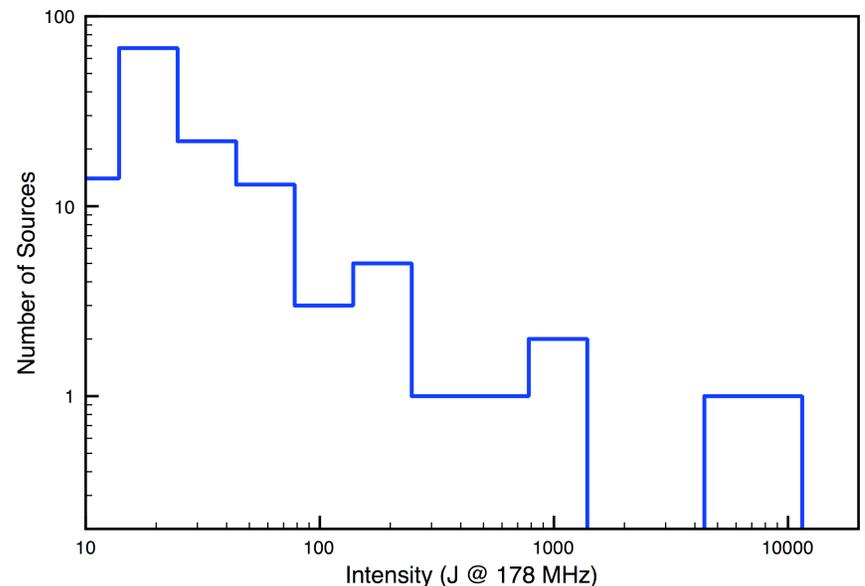
- Pulse LNA via capacitive coupling (Doesn't measure antenna match, cabling might be awkward)
- Excite feed via radiation (difficult to get in far field at a reasonable angle)
- Balloon on a tether (labor intensive, need position)
- Airplane (expensive, need to track position)
- Satellites (no control, fixed frequency)

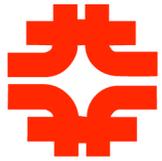


Spatial: Point Sources

- Many 10 to 100 J point sources
- Good absolute calibrators:
positions are known much better than the CRT resolution and the fluxes are known accurately.
- Source is within aperture for limited period of time
- Good S/N if angular resolution is adequate.
 - 1J @ 178 MHz = 30 °K over 20'x20'
 - 1J @ 178 MHz = 15 m°K over 90°x2.5°
- Accuracy is limited by S/N

Intensities of 3C catalog sources





Spatial: Full Sky

- Simply require that visibilities with the same baseline be equal, *i.e.*, for all m, n

$$\langle a_m a_{m+\ell}^* \rangle = \langle a_n a_{n+\ell}^* \rangle$$

- Many advantages over using point sources
 - No knowledge of the sky is required
 - Variable sources do not affect the result
 - Integration time does not depend on aperture
- Calibration depends on sky pattern if the feed responses are not identical.
- Calibration limited to relative gain responses.



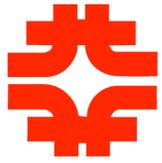
Frequency & Polarization

- All-sky surveys (c.f. Oliveira-Costa 2008 compilation)
- Measurements of single point sources (e.g., Kellermann 1969)
- Are there any calibrated broad spectrum measurements?
- We will have to *assume* that the average sky has a smooth spectrum and fit to that model.
- We will have to *assume* that the average sky is unpolarized.
- Polarized sources will be assumed to have a smooth power spectrum.



Calibration from FFT data

- With a known sky, we can determine at most 1 parameter per beam. We can't, for example, determine a complex gain for each channel.
- It is “easy” to measure the (absolute) antenna response in the azimuthal direction since the sky rolls across the antenna pattern.
- The polar angle calibration is more problematic
 - Known sky
 - Known point sources
 - Artificial sources (satellites, airplanes, balloons)



Dithering

for Increased Spatial Resolution

- In principle, we can achieve higher spatial resolution by changing the telescope pointing by an amount that is small compared to the telescope resolution.
- Higher resolution comes at a price of S/N: you get higher resolution by subtracting overlapping bins.
- The azimuthal dithering happens naturally: the only price is how finely you want to log the data.
- The declination dithering requires the addition of a phase shift to each channel: this can be done digitally.

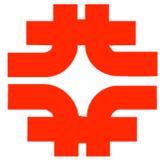


FFT Concept

$$|d_n|^2 = \frac{1}{N^2} \sum_{\ell=1}^N \sum_{m=1}^N e^{2\pi i(\ell-m)/N} a_{\ell} a_m^*$$

$$P = \sum_{m=1}^N a_m a_m^*$$

$$|d'_n|^2 = \frac{1}{N^2} \sum_{\ell=1}^N \sum_{m=1}^N e^{2\pi i(\ell-m)/N} a_{\ell} a_m^* - P$$

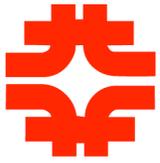


CRT Simulated Data

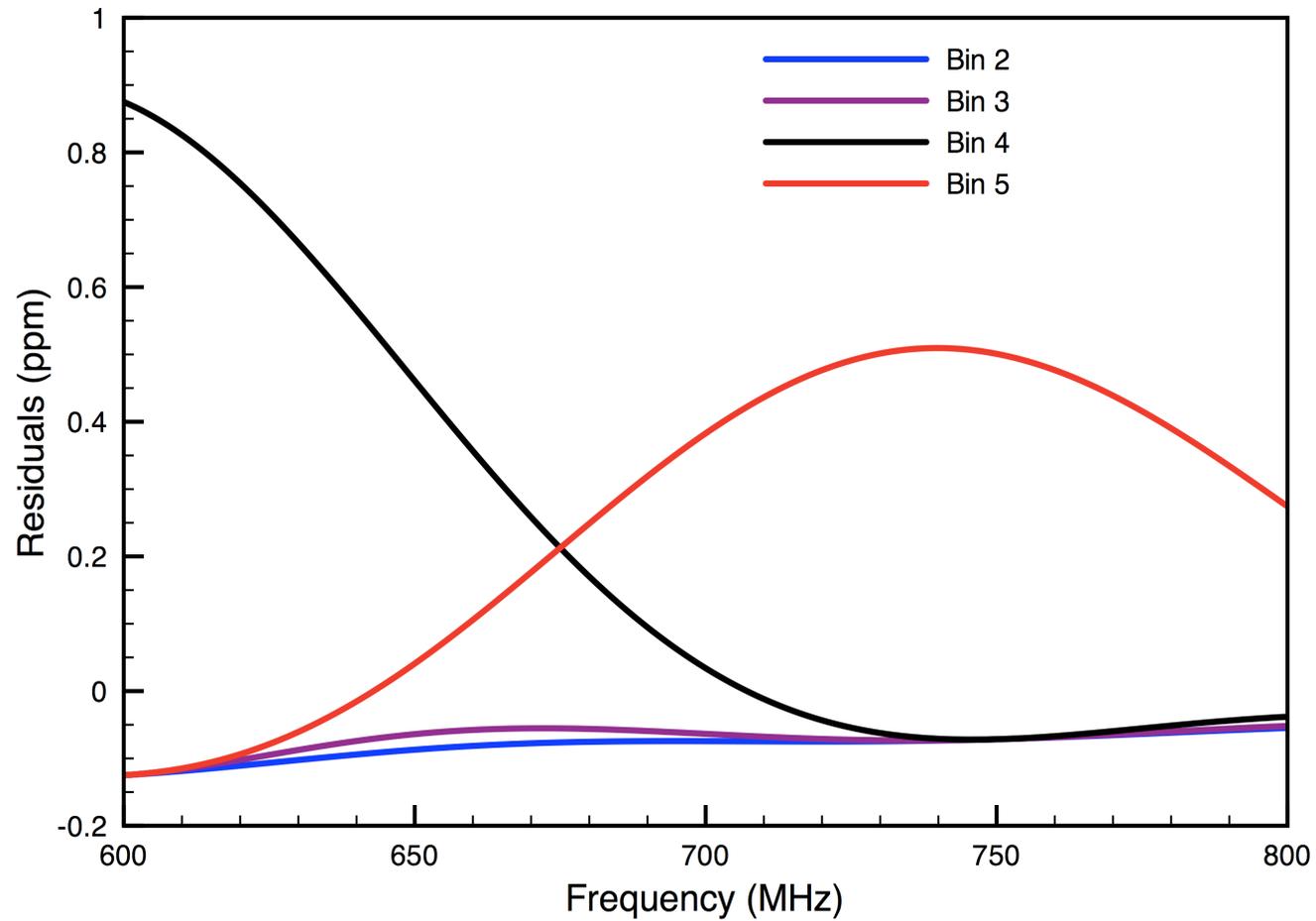
Simulated point source data for 8 azimuthal bins at $\Delta f=50$ kHz

| | | | | | | | | | |
|----|----------|----------|----------|----------|---------|----------|----------|----------|------------------|
| 0 | -0.12500 | -0.12500 | -0.12500 | -0.12500 | 0.87500 | -0.12500 | -0.12500 | -0.12500 | Frequency bins → |
| 1 | -0.12497 | -0.12497 | -0.12497 | -0.12497 | 0.87482 | -0.12497 | -0.12497 | -0.12497 | |
| 2 | -0.12495 | -0.12495 | -0.12495 | -0.12495 | 0.87463 | -0.12495 | -0.12495 | -0.12495 | |
| 3 | -0.12492 | -0.12492 | -0.12492 | -0.12492 | 0.87445 | -0.12492 | -0.12492 | -0.12492 | |
| 4 | -0.12490 | -0.12490 | -0.12490 | -0.12489 | 0.87427 | -0.12489 | -0.12490 | -0.12490 | |
| 5 | -0.12487 | -0.12487 | -0.12487 | -0.12487 | 0.87408 | -0.12487 | -0.12487 | -0.12487 | |
| 6 | -0.12484 | -0.12484 | -0.12484 | -0.12484 | 0.87390 | -0.12484 | -0.12484 | -0.12484 | |
| 7 | -0.12482 | -0.12482 | -0.12482 | -0.12481 | 0.87371 | -0.12481 | -0.12482 | -0.12482 | |
| 8 | -0.12479 | -0.12479 | -0.12479 | -0.12478 | 0.87352 | -0.12478 | -0.12479 | -0.12479 | |
| 9 | -0.12476 | -0.12476 | -0.12476 | -0.12476 | 0.87333 | -0.12476 | -0.12476 | -0.12476 | |
| 10 | -0.12474 | -0.12474 | -0.12474 | -0.12473 | 0.87315 | -0.12473 | -0.12474 | -0.12474 | |
| 11 | -0.12471 | -0.12471 | -0.12471 | -0.12470 | 0.87296 | -0.12470 | -0.12471 | -0.12471 | |
| 12 | -0.12469 | -0.12469 | -0.12468 | -0.12467 | 0.87277 | -0.12467 | -0.12468 | -0.12469 | |
| 13 | -0.12466 | -0.12466 | -0.12466 | -0.12464 | 0.87258 | -0.12464 | -0.12466 | -0.12466 | |
| 14 | -0.12463 | -0.12463 | -0.12463 | -0.12461 | 0.87238 | -0.12461 | -0.12463 | -0.12463 | |
| 15 | -0.12461 | -0.12461 | -0.12460 | -0.12458 | 0.87219 | -0.12458 | -0.12460 | -0.12461 | |
| 16 | -0.12458 | -0.12458 | -0.12458 | -0.12456 | 0.87200 | -0.12455 | -0.12458 | -0.12458 | |
| 17 | -0.12455 | -0.12455 | -0.12455 | -0.12453 | 0.87181 | -0.12453 | -0.12455 | -0.12455 | |
| 18 | -0.12453 | -0.12453 | -0.12452 | -0.12450 | 0.87161 | -0.12450 | -0.12452 | -0.12453 | |
| 19 | -0.12450 | -0.12450 | -0.12449 | -0.12447 | 0.87142 | -0.12446 | -0.12449 | -0.12450 | |
| 20 | -0.12447 | -0.12447 | -0.12447 | -0.12444 | 0.87122 | -0.12443 | -0.12447 | -0.12447 | |

Azimuthal bins ->

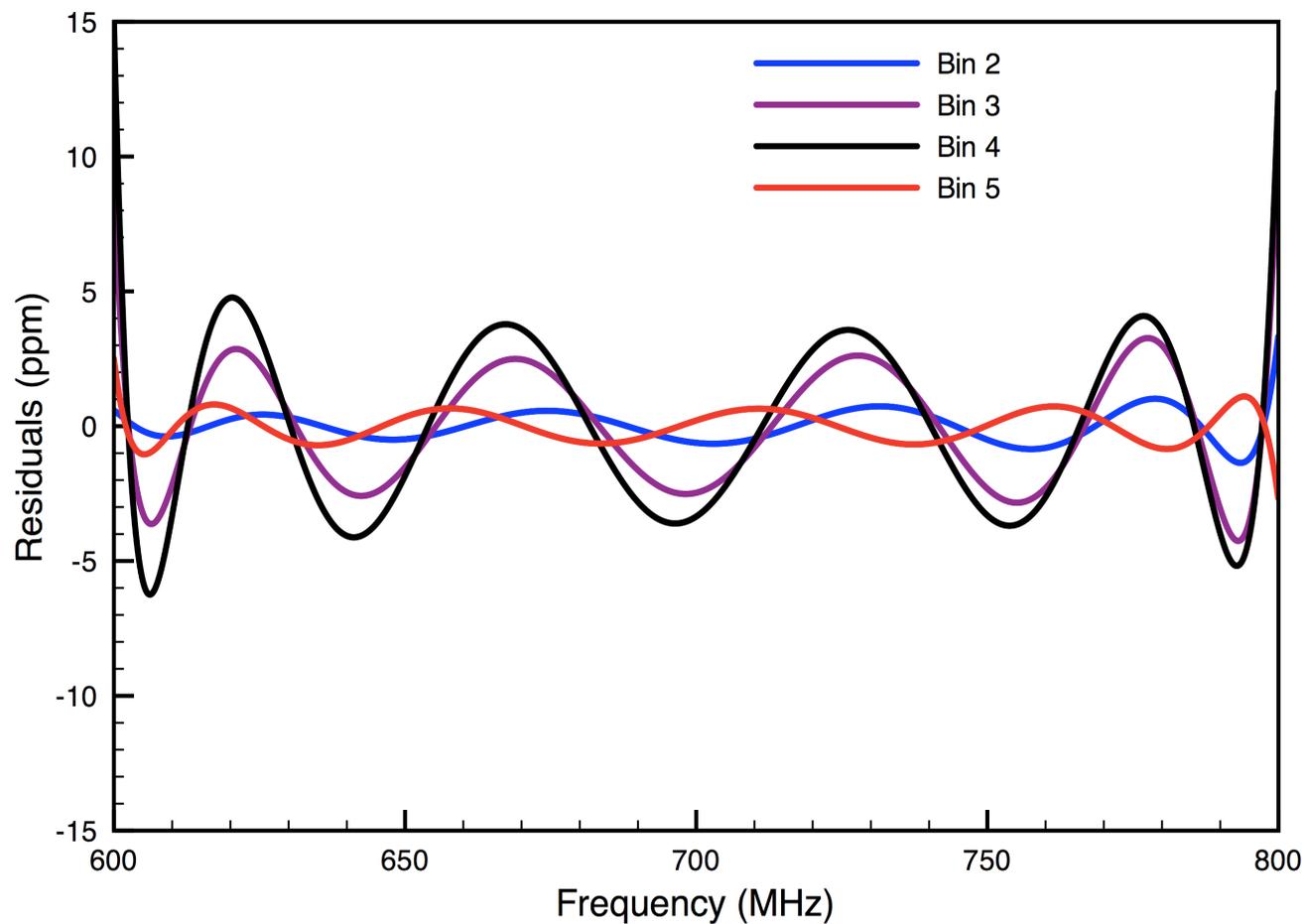


Bin Population vs Frequency





Residuals from Polynomial Fit





BAO Scale in Practical Units

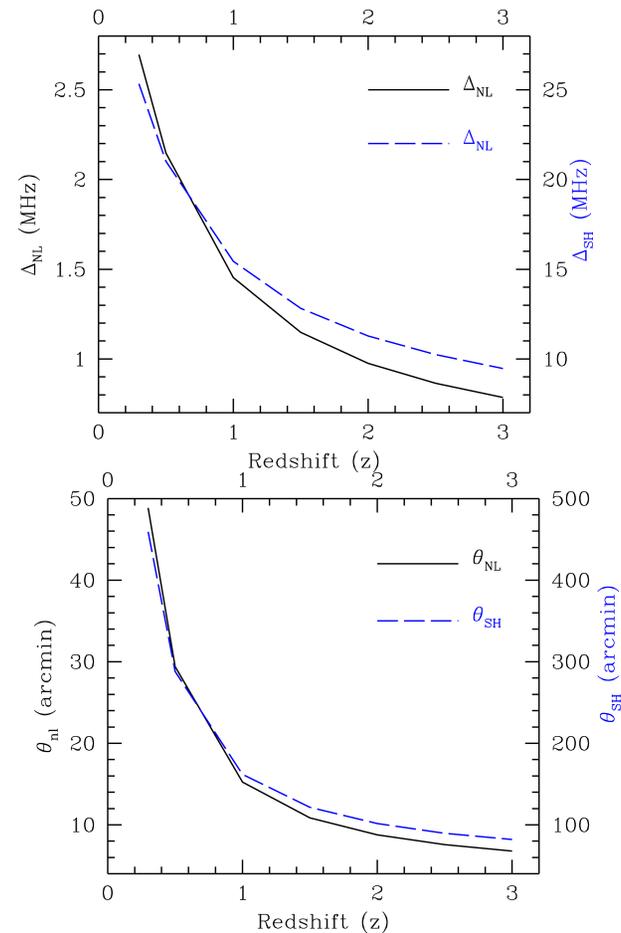
- The non-linear regime set the requirement for angular and frequency resolution.

- The sound horizon is the minimum coverage range for BAO, but...

- Synchrotron foreground

- Large scale structure

require much larger angle and frequency coverage.





Instrument Correction

- If we have an instrument model, correcting the data is straight-forward.
- The instrument model can be expressed as an $N \times N$ matrix, where N is the number of channels.
- Calibration of each of N^2 elements is probably not feasible.



Conclusions

- Data Acquisition seems straight-forward and relatively low cost.
- Control and monitoring seems straight-forward.
- Foreground subtraction is a key driver
 - Work is need to understand the existing literature.
 - We need a strawman strategy for CRT.
 - We need some experimental work.
- Spatial resolution requirements appear to be modest provided we don't need high precision ($\sim 10^{-5}$) for foreground subtraction.
- Some ideas have been developed for calibration.
- A simple approach to foreground subtraction seems promising, but in apparent contradiction to the conventional wisdom.



Sensitivity Calculations

Hee-Jong Seo
Work in Progress

